

Practice exam 2 problems

1

Approximate the first two derivatives of $y(x)$ at the given points using second order accurate finite differences (centered if possible).

x	-1	0	1	2
y	2	2	3	4
y'	-	-	-	-
y''	-	-	-	-

2

Given the following data, approximate the first four derivatives of $f(x)$ at $x = 1$ using centered finite differences.

x	-1	0	1	2	3
$f(x)$	1	2	4	3	2

3

(a) Find D_0^2 for Richardson extrapolation to estimate the derivative of $f(x)$ at $x = 1.1$, with initial step size $h_0 = 0.4$. Use the function values given below, and show at least 7 significant figures.

(b) What is the estimated fractional error in this obtained $f'(x)$?

x	0.5	0.6	0.7	0.8	0.9	1	1.1	1.2	1.3	1.4	1.5
$f(x)$	61255	67322	74199	81907	90488	100000	110513	122106	134870	148902	164311

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(a) Find D_0^2 for Richardson extrapolation to estimate the derivative of $f(x)$ at $x = 1$, with initial step size $\Delta_0 = 0.4$. Use the function values given below.

(b) What is the estimated relative error in this estimated $f'(x)$?

x	0.5	0.6	0.7	0.8	0.9	1	1.1	1.2	1.3	1.4	1.5
$f(x)$	70711	73602	77906	83651	90953	100000	111053	124456	140646	160169	183712

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Consider the composite trapezoid rule approximation T_{78} of $\int_0^1 x^{95} dx$.

(a) Does T_{78} overestimate or underestimate the exact value? Explain how you know.

(b) Find a bound for the absolute error in T_{78} using the result that $\text{Error}(T_N) \leq \frac{M(b-a)^3}{12N^2}$, where M is the least upper bound for all absolute values of the second derivatives over $[a, b]$ of the function being integrated.

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(a) Estimate the integral $\int_0^2 x^{10} dx$ using the simple Simpson's rule.

(b) Find the minimum number N of equal-width subdivisions needed to guarantee that the absolute error in the composite Simpson rule estimate for this integral is under 10^{-7} using the error bound $\frac{K_4(b-a)^5}{2880N^4}$.

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Estimate $I = \int_2^4 y(x) dx$ given the values below (a) using the simple Simpson rule,

(b) using the composite Simpson rule with $n = 2$ equal-length intervals.

(c) Based on (a) and (b), estimate what n would be needed for the absolute error in estimating I using the composite Simpson rule to be under 10^{-3} .

x	2	2.5	3	3.5	4
$y(x)$	100	67	50	40	33

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Estimate the integral of $e^{(x^2)}$ between $a = 0$ and $b = 1$ using Simpson's rule with

(a) one subinterval,

(b) two subintervals.

(c) Estimate your fractional error based on the difference between the two results.

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An irregular lot is 100 ft long, and its width as measured at various points is as follows:

position (ft)	0	25	50	75	100
width (ft)	10	15	20	23	25.

Estimate the lot's area as accurately as possible using the composite Simpson rule.

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Starting from standstill at $t = 0$, the acceleration of an elevator is measured as

$t(\text{s})$	0	5	10	15	20	23	30
$a(\text{m/s}^2)$	0	2.2	3.6	5.2	6.0	-4.0	-8.1

- (a) Estimate the velocity at $t = 20$ using the composite trapezoid rule.
- (b) Write a Python script to estimate the velocity at $t = 20$ by fitting an interpolating polynomial to the data and integrating it.

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Write Python code to estimate the probability of falling between $x = 1$ and $x = 2$ for the probability density function $p(x) = e^{-(e^{-x}+x)}$.

12

Calculate the Romberg integration estimator R_0^2 of

$$\int_0^1 \frac{x^3}{x+1} dx.$$

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- (a) Use Romberg integration with $j_{\max} = 2$ to estimate

$$I = \int_0^2 \frac{x}{x+3} dx.$$

- (b) Estimate the relative error based on the difference between your two most accurate estimates.

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- (a) Fill in the first 3 levels of Romberg integration to estimate the integral of \sqrt{x} for x between 0 and 3.
- (b) Estimate the absolute error based on the difference between the two most accurate estimates above.
- (c) Find the actual absolute error of the most accurate estimate above compared to the analytic integral.

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- (a) Use Romberg integration with $j_{\max} = 3$ to estimate $I = \int_0^1 (e^x - 4x)dx$.
(b) Find the solution analytically, and based on this calculate the fractional error of part a.

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Use Romberg integration with $j_{\max} = 2$ to estimate $I = \int_0^2 \frac{x^2}{x^2+3}dx$.

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- Use the (explicit) Euler method to solve for $y(x = 1)$ if $y(x = 0) = 2$ and $y' = \frac{y}{x^2+2}$.
(a) With step size $h = 1$.
(b) With step size $h = 0.5$.
(c) Explain how you can estimate the fractional error in your solution using the above results.

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Estimate $y(5)$ for the initial-value problem

$$\frac{dy}{dt} = \sqrt{y} - t + 1, \quad y(1) = 3$$

using Euler's method (RK1) with step size $h = 1$.

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- (a) Use Euler's method with step size $h = 1/4$ to estimate $y(1)$ given $\frac{dy}{dt} = -2y, y(0) = 3$.
(b) Find the absolute error of this estimate compared to the analytic solution $y(t) = 3e^{-2t}$.
(c) Write Python code to solve for and display $y(1)$ using `ode45`.

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- (a) Use Euler's method with a step size h of $1/3$ to estimate $y(t = 1)$ if $y(t = 0) = 0, dy/dt = y + 2\sqrt{t}$.
(b) Estimate $y(t = 1)$ for the same problem with the RK4 method and $h = 1$.
(c) Write Python code that uses `scipy.integrate.solve_ivp` to estimate $y(t = 1)$ and displays the estimated value.

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Let $y(t)$ be the solution to $y' = 4te^{-y}$ satisfying $y(0) = 3$. Use Euler's Method with time step $h = 0.1$ to approximate $y(0.1), y(0.2), \dots, y(0.5)$.

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- (a) Use Euler's method with a step size h of $1/3$ to estimate $y(t = 1)$ if $y(t = 0) = 0, dy/dt = y + 4t^2$.
- (b) Estimate $y(t = 1)$ for the same problem with the RK4 method and $h = 1$.

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Estimate $y(3)$ for the initial-value problem

$$y' = \frac{\sqrt{y}}{2}, y(1) = 1$$

using Heun's method (RK2) with step size $h = 1$.

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Estimate $y(3)$ for the initial-value problem $y'' = \frac{\sqrt{y}}{2}, y(1) = 1, y'(1) = 0$ using Heun's method (RK2) with step size $h = 1$.

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- (a) Use 1 step of the RK4 method to solve for $y(x = 6)$ if $y(x = 0) = 2$ and $y' = x\sqrt{y}$.
- (b) Write Python code for solving this problem and displaying the result.

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Estimate $y(t = 2)$ if $y(t = 0) = 0, dy/dt = -2y + 3\sqrt{t}$ with the RK4 method and $h = 1$.

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- (a) Use the implicit Euler method with step size $h = 1/6$ to estimate $y(1)$ given $\frac{dy}{dt} = -2y, y(0) = 3$.
- (b) Find the absolute error of the estimated $y(1)$ compared to the analytic solution $y(t) = 3e^{-2t}$.
- (c) Write Python code to solve for and display $y(1)$.

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Estimate $y(3)$ for the initial-value problem

$$y'' = \frac{\sqrt{y}}{2}, y(1) = 5, y'(1) = 0$$

using Heun's method (RK2) with step size $h = 1$.

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For the mass-spring system with driving force as given below, use 2 equal-length steps of Euler's method to estimate $x(t)$ at $t = 1$. The initial conditions at $t = 0$ are $x = 1, x' = 0$.

$$x'' + x = 3 \cos(t)$$

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(a) Write a Python function, similar to the RK2 one we did in lab, to implement Euler's method for solving a system of first-order differential equations with given initial values. The first line should be

```
def rk1(f, tspan, y0, n):
```

(b) Write a Python script that uses this `rk1` and a step size $h = 0.01$ to display $y(2)$ if $y'' = \sin(1/y)$ and $y(1) = 10, y'(1) = 3$.

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Write a Python script that solves numerically the initial-value problem

$$y'' + y' + y^2 = 1, y(0) = 2, y'(0) = -2$$

and plot $y(t)$ for $0 \leq t \leq 10$.

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Write a Python script that (a) numerically estimates $\Theta(2)$ if $\Theta'' = -9\Theta$ and $\Theta(0) = 1, \Theta'(0) = 0$ and (b) finds the absolute error of this estimate relative to the analytic solution $\Theta(t) = \cos(3t)$.

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(a) Set up a system of linear equations (in matrix form) using finite difference with $n = 4$ to solve the equation $y'' + y' = x + 2$ subject to the boundary conditions $y(x = 0) = 0$ and $y(x = 3) = 1$.

(b) Solve this system using Gaussian elimination or LU decomposition, and sketch $y(x)$.

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Set up a linear system in matrix form to solve the boundary-value problem $y'' + 5y' = 10$, $y(0) = 1$, $y(4) = 3$ for values of the function $y(x)$, using second-order-accurate centered finite-difference approximations for the derivatives, with $n=5$. You do not need to solve the linear system.

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Set up a system of algebraic equations (in matrix form) using finite difference with $n = 5$ for $y'' - y' + y = 2$ subject to the boundary conditions $y(0) = 0$ and $y'(3) = 2$. Use second-order-accurate (centered where possible) finite difference approximations. You only need to write down the system, not to solve it.

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Set up a system of algebraic equations (in matrix form) using finite difference with $n = 5$ to solve $y'' + y' - y = 4$ subject to the boundary conditions $y(x = 0) = 0$ and $y'(x = 3) = 2$. Use second-order-accurate (centered where possible) finite difference approximations. For full credit, solve this system and sketch $y(x)$.

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Set up a system of algebraic equations (in matrix form) using finite difference with $n = 5$ to solve $y'' + y' + y = 2$ subject to the boundary conditions $y(x = 0) = 0$ and $y'(x = 1) = 2$. For full credit, solve this system and sketch $y(x)$.

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- (a) Set up a system of linear algebraic equations (in matrix form) using finite difference with $n = 5$ to solve $y'' + y = x + 4$ subject to the boundary conditions $y(x = 0) = 0$ and $y(x = 5) = 2$. Explain what the unknowns in this system represent.
- (b) Write Python code to solve the same problem numerically and to plot $y(x)$.

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- (a) Set up a system of linear equations (in matrix form) using finite difference with $n = 4$ to solve the equation $y'' - y = x + 3$ subject to the boundary conditions $y(x = 0) = 0$ and $y(x = 2) = 0$.
- (b) Solve this system (for example, using Gaussian elimination) and sketch $y(x)$.

(c) Write Python code to solve the boundary-value problem numerically and plot $y(x)$.

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(a) Set up a system of linear equations (in matrix form) using finite difference with $n = 6$ to solve the equation $y'' + 3y' = y + 4$ subject to the boundary conditions $y(x = 0) = 0$ and $y(x = 1) = 0$.

(b) Solve this system (for example, using Gaussian elimination) and sketch the solution $y(x)$.