10. Regression

Outline

- Definition
- Example applications
- Least squares
- Solving linear problems
- Diagnostics (R^2 , adjusted R^2 , AIC)

Definition

- ► Fit a function of (some) given type, say *f*, approximately through given points (*x_i*, *y_i*) so that for the given points, *f*(*x_i*) ≈ *y_i*, *i* = 1, 2, ... *n*
- This function is usually intended to predict y given a predictor value x (this x can actually be a vector that contains several different relevant predictors)

Example applications

- Forecasting travel time for a route based on predictors such as time of day, day of week, closeness to holiday, amount of construction ...
- Forecasting transit ridership based on similar factors, and perhaps ones that change more slowly such as population density, amount of commercial space, and economic activity
- Estimating house prices from predictors such as size, age, location, ...

Least squares

- ► If the points are grouped as vectors x, y, the residual vector of the fitted function is r = y f(x) (i.e. r_i = y_i f(x_i))
- We'd like r to be close to all zeros (which would be the case for interpolation, where y_i = f(x_i))
- Problem: Out of all the functions *f* in the given type, find the one that has the smallest the residual sum of squares, RSS = *r*^T*r* = ∑_{i=1}ⁿ r_i²

Linear least squares

- Suppose the function type is such that we can write f(x) = A \beta (linear regression)
 - ▶ **A** is a known *n* × *m* design matrix for the given **x**
 - $oldsymbol{eta}$ is an unknown m imes 1 vector of 'parameters'

$$\blacktriangleright \text{ So } f(x_i) = A_{i,1}\beta_1 + A_{i,2}\beta_2 + \ldots A_{i,m}\beta_m$$

Then we can find using linear algebra methods the value of β that minimizes the RSS for the given x and y

The normal equations

 $A^T A \beta = A^T y$ is the system of *normal equations* for a linear regression problem. Solving it for β gives us the least squares (lowest RSS) set of parameter values.

Example problem

Suppose our function type is $f(u, v) = \beta_1 u + \beta_2 \sqrt{v}$. This is linear in the unknown β_i , so we can write $f(u, v) = A\beta$, where the

design matrix
$$\boldsymbol{A}$$
 is
$$\begin{pmatrix} u_1 & \sqrt{v_1} \\ u_2 & \sqrt{v_2} \\ u_3 & \sqrt{v_3} \\ u_4 & \sqrt{v_4} \\ u_5 & \sqrt{v_5} \\ u_6 & \sqrt{v_6} \end{pmatrix} = \begin{pmatrix} 2 & 2 & 1 \\ 1 & 1 \\ 6 & \sqrt{3} \\ 0 & 1 \\ 2 & 0 \\ 1 & \sqrt{14} \end{pmatrix}$$
The normal equations are then
$$\begin{pmatrix} 46 & 19.134 \\ 19.134 & 23 \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} = \begin{pmatrix} 209 \\ 102.97 \end{pmatrix}$$
Resulting in $\boldsymbol{\beta} = \begin{pmatrix} 4.100 \\ 1.066 \end{pmatrix}$

Diagnostics

- These are measures of how well a function fits given y values, meant to give an indication of how good it might be as a predictor
- $R^2 = 1 \frac{\text{RSS}}{\text{TSS}}, \text{ where the total sum of squares TSS is } (\mathbf{y} \bar{y})^T (\mathbf{y} \bar{y}), \text{ with } \bar{y} \text{ the average value of } \mathbf{y}$
- Adjusted R^2 : $R_a^2 = 1 \frac{n-1}{n-m} \frac{\text{RSS}}{\text{TSS}}$, where *n* is the number of data points and *m* is the number of unknown parameters in β
- Akaike information criterion (AIC): nlog(RSS/n) + 2mn/(n - m - 1) (lower value denotes better fit)
- ▶ R_a^2 and AIC include *m* as well as RSS in their formulas to reflect that all else being equal, a more complicated function type (with more parameters that need to be determined) will not be as good at predicting unknown values

Example

- For the function type $f(u, v) = \beta_1 u + \beta_2 \sqrt{v}$, the least-squares β give RSS = 12.3, $R^2 = 0.966$, $R_a^2 = 0.957$, AIC = 12.3
- Changing the function type to one with another parameter with $g(u, v) = \beta_1 u + \beta_2 \sqrt{v} + \beta_3$, gives RSS = 10.4, $R^2 = 0.971$, $R_a^2 = 0.952$, AIC = 21.3
- Although R² improves with the additional parameter, R²_a and AIC both worsen, implying that this function type may not be better at predicting y given the points available for fitting

Nonlinear least squares

- The regression model or function type, f(β; x), may also be nonlinear in β – for example, it might look like x^β or cos(βx).
- In that case, we can still look for the least-squares values of β, but we typically need to use iterative numerical methods to approximate it, instead of just solving a linear system.
- Once the least-squares value of β is found, R² and other diagnostics can be calculated following the same formulas as before.